# Virtual Element Method for general second-order elliptic problems on polygonal meshes 

Rainer Schneckenleitner<br>JKU Linz<br>January 08, 2019

## Overview

(1) The Problem
(2) Variational Formulation
(3) VEM Approximation
(4) Error Estimates
(5) Numerical Experiments

## Outline

(1) The Problem

## (2) Variational Formulation

(3) VEM Approximation

4 Error Estimates
(5) Numerical Experiments

## Assumptions

- Let $\Omega \subset \mathbb{R}^{2}$ be a bounded, convex and polygonal domain with boundary $\Gamma$
- Let $\kappa \in L^{\infty}(\Omega)$ and $\gamma \in L^{\infty}(\Omega)$ be smooth functions $\Omega \rightarrow \mathbb{R}$ with $\kappa(x) \geq \kappa_{0}>0$ for all $x \in \Omega$
- Let $b: \Omega \rightarrow \mathbb{R}^{2}$ be a smooth vector-valued function, $b \in\left[L^{\infty}(\Omega)\right]^{2}$
- The problem

$$
\begin{array}{rrr}
\mathcal{L} p:=\operatorname{div}(-\kappa \nabla p+b p)+\gamma p=f & \text { in } H^{-1}(\Omega),  \tag{1}\\
p=0 & \text { on } \Gamma
\end{array}
$$

is solvable for any $f \in H^{-1}(\Omega)$ and the estimates

$$
\|p\|_{1, \Omega} \leq C\|f\|_{-1, \Omega}
$$

and

$$
\|p\|_{2, \Omega} \leq C\|f\|_{0, \Omega}
$$

hold with a constant $C$ independent of $f$.

## Remarks

- Existence and uniqueness is assumed!
- Also existence and uniqueness for the adjoint operator equation
- The following analysis do also hold for $\kappa$ being a tensor


## Outline

## (1) The Problem

(2) Variational Formulation
(3) VEM Approximation
(4) Error Estimates
(5) Numerical Experiments

## Variational Formulation

## Definition

Define

$$
\begin{aligned}
a(p, q) & :=\int_{\Omega} \kappa \nabla p \nabla q d x \\
b(p, q) & :=-\int_{\Omega} p(b \cdot \nabla q) d x \\
c(p, q) & :=\int_{\Omega} \gamma p q d x \\
B(p, q) & :=a(p, q)+b(p, q)+c(p, q)
\end{aligned}
$$

## Variational formulation

Find $p \in H_{0}^{1}(\Omega)$ such that

$$
\begin{equation*}
B(p, q)=(f, q)_{0} \quad \forall q \in H_{0}^{1}(\Omega) \tag{2}
\end{equation*}
$$

## Variational Formulation

- The assumptions above imply that $B(\cdot, \cdot)$ fulfills

$$
|B(p, q)| \leq M\|p\|_{1}\|q\|_{1} \text { for } p, q \in H^{1}(\Omega)
$$

and

$$
\sup _{q \in H_{0}^{1}} \frac{B(p, q)}{\|q\|_{1}} \geq C_{B}\|p\|_{1} \text { for } p \in H_{0}^{1}(\Omega)
$$

for some $C_{B}>0$ independent of p .

## Outline

## (1) The Problem

## (2) Variational Formulation

(3) VEM Approximation
(4) Error Estimates
(5) Numerical Experiments

## The Virtual Element Space

- Let $\mathcal{T}_{h}$ be a decomposition of $\Omega$ into star-shaped polygons $E$, s.t.,
(1) every $E$ is star-shaped w.r.t. every point of a disk with radius $\rho^{E} h_{E}$
(2) every edge $e$ of $E$ has length $|e| \geq \rho^{E} h_{E}$
- Let $\mathcal{E}_{h}$ denote the set of edges $e$ of $\mathcal{T}_{h}$
- $h_{E}=\operatorname{diam}(E), h=\max _{E \in \mathcal{T}_{h}} h_{E}$


## The Virtual Element Space

## Definition (Preliminary local space)

For any integer $k \geq 1$ and any element $E$ we define the preliminary local space by

$$
\tilde{\mathcal{Q}}_{h}^{k}(E):=\left\{q \in H^{1}(E):\left.q\right|_{e} \in \mathbb{P}_{k}(e) \forall e \in \partial E, \Delta q \in \mathbb{P}_{k-2}(E)\right\}
$$

## Definition

For all $q_{h} \in \tilde{\mathcal{Q}}_{h}^{k}(E)$ we define the linear operators

- $\left(D_{1}\right)$ the values $q_{h}\left(V_{i}\right)$ at the vertices $V_{i}$ of $E$ and for $k \geq 2$
- $\left(D_{2}\right)$ the edge moments $\int_{e} q_{h} p_{k-2} d s, p_{k-2} \in \mathbb{P}_{k-2}(e)$, on each $e$ of E,
- $\left(D_{3}\right)$ the internal moments $\int_{E} q_{h} p_{k-2} d x, p_{k-2} \in \mathbb{P}_{k-2}(E)$.


## The Virtual Element Space

- For each $E$ and all $k$ the operators $D_{1}-D_{3}$ satisfy

$$
\left\{q \in \mathbb{P}_{k}(E)\right\} \wedge\left\{D_{i}(q)=0, i=1,2,3\right\} \Rightarrow\{q=0\}
$$

- These properties allow to construct a projection $\tilde{\mathcal{Q}}_{h}^{k}(E) \rightarrow \mathbb{P}_{k}$
- Set $D q_{h}:=\left(D_{1}-D_{3}\right)\left(q_{h}\right)$ and choose suitable symmetric, positive bilinear form $\mathcal{G}$
- For $q_{h} \in \tilde{\mathcal{Q}}_{h}^{k}(E)$ we define $\Pi_{k}^{\mathcal{G}} q_{h}$ as the unique solution of

$$
\mathcal{G}\left(D q_{h}-D \Pi_{k}^{\mathcal{G}} q_{h}, D z\right)=0 \quad \forall z \in \mathbb{P}_{k}
$$

## The Virtual Element Space

- Recall $\Pi_{k}^{\nabla}$ from the last 2 Seminars:

For any $q \in H_{0}^{1}(\Omega)$ the function $\Pi_{k}^{\nabla} q$ on each $E$ is in $\mathbb{P}_{k}(E)$ and is defined by

$$
\left(\nabla\left(\Pi_{k}^{\nabla} q-q\right), \nabla p_{k}\right)_{0, E}=0
$$

and

$$
\int_{\partial E}\left(\Pi_{k}^{\nabla} q-q\right) d s=0
$$

for all $p_{k} \in \mathbb{P}_{k}$.

- For all $q_{h} \in \tilde{\mathcal{Q}}_{h}^{k}(E)$ the polynomial $\Pi_{k}^{\nabla} q_{h}$ can be computed using only the values of $D$ calculated on $q_{h}$


## The Virtual Element Space

## Definition (Virtual element space)

The local virtual element space is defined by

$$
\begin{aligned}
\mathcal{Q}_{h}^{k}(E):=\left\{q \in \tilde{\mathcal{Q}}_{h}^{k}(E): \int_{E} q p_{k} d x=\int_{E}\left(\Pi_{k}^{\nabla} q\right) p_{k} d x\right. & \\
\forall & \left.\forall p_{k} \in\left(\mathbb{P}_{k} \backslash \mathbb{P}_{k-2}(E)\right)\right\}
\end{aligned}
$$

where $\left(\mathbb{P}_{k} \backslash \mathbb{P}_{k-2}(E)\right)$ denotes the polynomials in $\mathbb{P}_{k}(E)$ that are $L^{2}(E)$ orthogonal to $P_{k-2}(E)$.

The global virtual element space is

$$
\mathcal{Q}_{h}^{k}:=\left\{q \in H_{0}^{1}(\Omega):\left.q\right|_{E} \in \mathcal{Q}_{h}^{k}(E) \forall E \in \mathcal{T}_{h}\right\}
$$

## The Virtual Elemnt Space

- Also recall $\Pi_{k}^{0}$ the $L^{2}$ projection onto $\mathbb{P}_{k}$ defined by

$$
\left(q-\Pi_{k}^{0} q, p_{k}\right)_{0, E}=0 \quad \forall p_{k} \in \mathbb{P}_{k}
$$

- The set of operators $(D)$ is a set of dofs for $\mathcal{Q}_{h}^{k}(E)$
- The dofs $(D)$ define an interpolation operator
- The local virtual element space $\mathcal{Q}_{h}^{k}(E)$ satisfies
(1) $\mathbb{P}_{k}(E) \subseteq \mathcal{Q}_{h}^{k}(E)$
(2) for all $q_{h} \in \mathcal{Q}_{h}^{k}(E)$
- the function $\Pi_{k}^{\nabla} q_{h}$,
- the function $\Pi_{k}^{0} q_{h}$ and
- the vector function $\Pi_{k-1}^{0} \nabla q_{h}$
can be computed from the dofs $(D)$ of $q_{h}$
The proofs can be found in $[1,2,3]$.


## The Discrete Problem

- Denote by $a^{E}(\cdot, \cdot), b^{E}(\cdot, \cdot), c^{E}(\cdot, \cdot)$ and $B^{E}(\cdot, \cdot)$ the restrictions of the previously defined bilinear forms to $E$
- Let $S^{E}\left(p_{h}, q_{h}\right)$ be a symmetric bilinear form on $\mathcal{Q}_{h}^{k}(E) \times \mathcal{Q}_{h}^{k}(E)$
- $S^{E}(\cdot, \cdot)$ scales like $a^{E}(\cdot, \cdot)$ on the kernel of $\Pi_{k}^{\nabla}$, i.e., there exist $0<\alpha_{*} \leq \alpha^{*}$ independent of $h$ such that

$$
\alpha_{*} a^{E}\left(q_{h}, q_{h}\right) \leq S^{E}\left(q_{h}, q_{h}\right) \leq \alpha^{*} a^{E}\left(q_{h}, q_{h}\right)
$$

for all $q_{h} \in \mathcal{Q}_{h}^{k}(E)$ with $\Pi_{k}^{\nabla} q_{h}=0$.

## The Discrete Problem

## Definition

Define on each $E \in \mathcal{T}_{h}$ and for every $p_{h}, q_{h} \in \mathcal{Q}_{h}^{k}(E)$ the local forms

$$
\begin{aligned}
& a_{h}^{E}\left(p_{h}, q_{h}\right):=\int_{E} \kappa\left[\Pi_{k-1}^{0} \nabla p_{h}\right] \cdot\left[\Pi_{k-1}^{0} \nabla q_{h}\right] d x+ \\
& S^{E}\left(\left(\mathcal{I}-\Pi_{k}^{\nabla}\right) p_{h},\left(\mathcal{I}-\Pi_{k}^{\nabla}\right) q_{h}\right), \\
& b_{h}^{E}\left(p_{h}, q_{h}\right):=-\int_{E}\left[\Pi_{k-1}^{0} p_{h}\right]\left[b \cdot \Pi_{k-1}^{0} \nabla q_{h}\right] d x, \\
& c_{h}^{E}\left(p_{h}, q_{h}\right):=\int_{E} \gamma\left[\Pi_{k-1}^{0} p_{h}\right]\left[\Pi_{k-1}^{0} q_{h}\right] d x, \\
&\left(f_{h}, q_{h}\right)_{E}:=\int_{E} f \Pi_{k-1}^{0} q_{h} d x, \\
& B_{h}^{E}\left(p_{h}, q_{h}\right):=a_{h}^{E}\left(p_{h}, q_{h}\right)+b_{h}^{E}\left(p_{h}, q_{h}\right)+c_{h}^{E}\left(p_{h}, q_{h}\right) .
\end{aligned}
$$

## The Discrete Problem

- For $p_{h}, q_{h} \in \mathcal{Q}_{h}^{k}$ the local forms are summed up


## Approximate Problem

Find $p_{h} \in \mathcal{Q}_{h}^{k}$ such that

$$
\begin{equation*}
B_{h}\left(p_{h}, q_{h}\right)=\left(f_{h}, q_{h}\right) \quad \forall q_{h} \in \mathcal{Q}_{h}^{k} . \tag{3}
\end{equation*}
$$

## The Discrete Problem

## Remarks

(1) Since $\Pi_{k}^{\nabla}$ is a projection

$$
S^{E}\left(\left(\mathcal{I}-\Pi_{k}^{\nabla}\right) p_{k},\left(\mathcal{I}-\Pi_{k}^{\nabla}\right) q_{h}\right)=0 \quad \forall p_{k} \in \mathbb{P}_{k}, \quad \forall q_{h} \in \mathcal{Q}_{h}^{k}(E)
$$

(2) The choice

$$
\begin{aligned}
& a_{h}^{E}\left(p_{h}, q_{h}\right):=\int_{E} \kappa\left[\nabla \Pi_{k}^{\nabla} p_{h}\right] \cdot\left[\nabla \Pi_{k}^{\nabla} q_{h}\right] d x+ \\
& S^{E}\left(\left(\mathcal{I}-\Pi_{k}^{\nabla}\right) p_{h},\left(\mathcal{I}-\Pi_{k}^{\nabla}\right) q_{h}\right)
\end{aligned}
$$

as supposed in [2] yiels heavy losses in the order of convergence for $k \geq 3$, if $\kappa \nabla p$ is a gradient this choice does work.

## Outline

## (1) The Problem

## (2) Variational Formulation

(3) VEM Approximation

4 Error Estimates

## (5) Numerical Experiments

## Preliminary Results

## Lemma (Continuity)

The bilinear form $B_{h}(\cdot, \cdot)$ is continuous in $\mathcal{Q}_{h}^{k} \times \mathcal{Q}_{h}^{k}$, that is,

$$
\left|B_{h}\left(p_{h}, q_{h}\right)\right| \leq C_{\kappa, b, \gamma}\left\|p_{h}\right\|_{1}\left\|q_{h}\right\|_{1} \quad p_{h}, q_{h} \in \mathcal{Q}_{h}^{k}
$$

where $C_{\kappa, b, \gamma}>0$ does not depend on $h$.

## Proof.

Whiteboard.

## Preliminary Results

## Lemma (Consistency)

For all $p$ sufficiently regular and for all $q_{h} \in \mathcal{Q}_{h}^{k}$ it holds

$$
\left|B^{E}\left(\Pi_{k}^{0} p, q_{h}\right)-B_{h}^{E}\left(\Pi_{k}^{0} p, q_{h}\right)\right| \leq C_{\kappa, b, \gamma} h_{E}^{k}\|p\|_{k+1, E}\left\|q_{h}\right\|_{1, E} \quad \forall E \in \mathcal{T}_{h} .
$$

## Proof.

For a proof see [3].

## Preliminary Results

## Lemma (Discrete inf-sup condition)

The bilinear form $B_{h}(\cdot, \cdot)$ satisfies the following condition: there exists an $h_{0}>0$ and a constant $\bar{C}_{B}$ such that, for all $h<h_{0}$ it holds

$$
\sup _{q_{h} \in \mathcal{Q}_{h}^{k}} \frac{B_{h}\left(p_{h}, q_{h}\right)}{\left\|q_{h}\right\|_{1}} \geq \bar{C}_{B}\left\|p_{h}\right\|_{1} \quad \forall p_{h} \in \mathcal{Q}_{h}^{k} .
$$

## Proof.

For a proof see [3].

## $H^{1}$ - estimate

## Theorem ( $H^{1}$-estimate)

For $h$ sufficiently small, the discrete problem (3) has a unique solution $p_{h} \in \mathcal{Q}_{h}^{k}$ and the error estimate

$$
\left\|p-p_{h}\right\|_{1} \leq C h^{k}\left(\|p\|_{k+1}+|f|_{k}\right)
$$

holds with a constant $C$ depending on $\kappa, b$ and $\gamma$ but independent of $h$.

## Proof.

$\left\|p-p_{h}\right\|_{1} \leq \underbrace{\left\|p-p_{\mathrm{I}}\right\|_{1}}_{\checkmark}+\underbrace{\left\|p_{\mathrm{I}}-p_{h}\right\|_{1}}_{\text {Whiteboard }}$.

## $L^{2}$ - estimate

## Theorem ( $L^{2}$-estimate)

For $h$ sufficiently small, the discrete problem (3) has a unique solution $p_{h} \in \mathcal{Q}_{h}^{k}$ and the error estimate

$$
\left\|p-p_{h}\right\|_{0} \leq C h^{k+1}\left(\|p\|_{k+1}+|f|_{k}\right)
$$

holds with a constant $C$ depending on $\kappa, b$ and $\gamma$ but independent of $h$.

## Proof.

For a proof see [3].

## Outline

## (1) The Problem

## (2) Variational Formulation

(3) VEM Approximation
(4) Error Estimates
(5) Numerical Experiments

## Numerical Experiments

- Consider problem (1) with the choice $\Omega=(0,1)^{2}$ and

$$
\kappa=\left(\begin{array}{cc}
y^{2}+1 & -x y \\
-x y & x^{2}+1
\end{array}\right), b=(x, y), \gamma=x^{2}+y^{3}
$$

and with $B C$ and rhs such that the exact solution is

$$
p_{e x}(x, y)=x^{2} y+\sin (2 \pi x) \sin (2 \pi y)+2
$$

- Comparison of $p_{\text {ex }}$ with the $L^{2}$-projection of $p_{h}$ to $\mathbb{P}_{k}$
- Comparison of $\left|p_{e x}-\Pi_{k}^{0} p_{h}\right|$ at the maximum of $p_{\text {ex }}$ which is approx. at $(0.781,0.766)$


## Numerical Experiments

- Four sequences of meshes with $25,100,400,1600$ polygons for each different mesh


Figure: Considered meshes Lloyd-0, Lloyd-100, square, concave

## Numerical Experiments

- Convergence results for $k=1$


Figure: Convergence rates for the current and the previous choice of $a_{h}^{E}(\cdot, \cdot)$, $L^{2}$ rate for previous $a_{h}^{E}(\cdot, \cdot)$ at bottom right

## Numerical Experiments

- Convergence results for $k=4$


Figure: Convergence rates for the current and the previous choice of $a_{h}^{E}(\cdot, \cdot)$, $L^{2}$ rate for previous $a_{h}^{E}(\cdot, \cdot)$ at bottom right

## References

[1] A. Ahmad, A. Alsaedi, F. Brezzi, L. Marini, and A. Russo. Equivalent projectors for virtual element methods. Computers \& Mathematics with Applications, 66(03):376-391, 2013.
[2] L. Beirão da Veiga, F. Brezzi, A. Cangiani, G. Manzini, L. Marini, and A. Russo. Basic Principles of virtual element methods. Mathematical Models and Methods in Applied Sciences, 23(01):199-214, 2013.
[3] L. Beirão da Veiga, F. Brezzi, L. Marini, and A. Russo. Virtual Element Method for general second-order elliptic problems on polygonal meshes. Mathematical Models and Methods in Applied Sciences, 26(04):729-750, 2016.

