

A convergent adaptive Algorithm for Poisson's Equation

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Preliminaries

Conforming Triangulation

- $\Omega \subset \mathbb{R}^2$: bounded, polygonal boundary

Conforming Triangulation

We say \mathcal{T} is a conforming triangulation of Ω iff the following properties hold:

- \mathcal{T} is a decomposition of Ω into a set of $N_{\mathcal{T}}$ open triangles T_j ,
- $\bar{\Omega} = \cup_{j=1}^{N_{\mathcal{T}}} \bar{T}_j$,
- $\bar{T}_i \cap \bar{T}_j$ is $\{ \text{empty, a vertex, a common edge} \}$.

Refinement of \mathcal{T}

Refinement of \mathcal{T}

We say \mathcal{T}_{k+1} is a refinement of a triangulation \mathcal{T}_k iff

- we decompose a subset of triangles in \mathcal{T}_k into subtriangles,
- the resulting decomposition is again a triangulation of Ω .

Basis functions and FE Spaces

Basis functions and FE Spaces

Let \mathcal{N}_k be the set of nodes in the mesh \mathcal{T}_k .

- $V_k := \text{span}\{\{\psi_q^k\}_{q \in \mathcal{N}_k}\},$
- $V_{0,k} := \text{span}\{\{\psi_q^k\}_{q \in \mathcal{N}_k \cap \partial\Omega}\},$
- $\psi_q^k(q') = c_q \delta_{qq'}$ for all $q, q' \in \mathcal{N}_k$.

Sequence of meshes property

Let $\{\mathcal{T}_k\}_{k \geq 0}$ be a sequence of meshes.

We assume that all triangles are of regular shape, i.e

$$\frac{d_{\mathcal{T}}}{d_{\mathcal{T}'}} \leq \sigma_0,$$

independent of $k \geq 0$.

Neighbours

The set of neighbours of a triangle T is given by

$$\omega_T := \{T' \in \mathcal{T}_k : \overline{T} \cap \overline{T'} \neq \emptyset\}.$$

This implies that

$$\frac{d_{\omega_T}}{d_T} \leq \sigma_1.$$

L^2 Projection P_k^1

Estimates for the L^2 Projection from H_0^1 to $V_{0,k}$

There are constants $C_0(\omega_T)$ and $C_{1,m}(\omega_T)$ such that

$$\begin{aligned}\|v - P_k^1 v\|_{L^2(T)} &\leq C_0(\hat{\omega}_T) d_{\omega_T} \|\nabla v\|_{L^2(\omega_T)}, \\ \|\nabla(v - P_k^1 v)\|_{L^2(T)} &\leq C_{1,m}(\hat{\omega}_T) d_{\omega_T}^m \|\nabla^{m+1} v\|_{L^2(\omega_T)} \quad m \in \{0, 1\}.\end{aligned}$$

Poincare inequality

Poincare inequality

For $u \in H_0^1(\Omega)$ it holds

$$\|u\|_{L^2(\Omega)} \leq C_P(\Omega) \|\nabla u\|_{L^2(\Omega)}.$$

The model problem

The model problem

Find $u \in H_0^1$ such that

$$\begin{aligned} -\Delta u &= f && \text{in } H^{-1}(\Omega) \\ u &= 0 && \text{on } \partial\Omega. \end{aligned}$$

The model problem

Find $u \in H_0^1$ such that

$$\int_{\Omega} \nabla u \nabla \phi = \int_{\Omega} f \phi \quad \forall \phi \in H_0^1(\Omega).$$

The discrete model problem

Find $u_k \in V_{0,k}$ such that

$$\int_{\Omega} \nabla u_k \nabla \phi_k = \int_{\Omega} f_k \phi_k \quad \forall \phi \in V_{0,k},$$

where f_k is some suitable approximation of f . We assume $f_k(q) = f(q)$ for all $q \in \mathcal{N}_k$.

Error reduction for linear finite elements

We want to

Solve \rightarrow Estimate \rightarrow Mark \rightarrow Refine

$$\mathcal{T}_0 \leq \mathcal{T}_1 \leq \mathcal{T}_2 \leq \mathcal{T}_3 \leq \dots$$

$$\|\nabla(u - u_0)\|_{L^2(\Omega)}^2 \geq \|\nabla(u - u_1)\|_{L^2(\Omega)}^2 \geq \|\nabla(u - u_2)\|_{L^2(\Omega)}^2 \geq \|\nabla(u - u_3)\|_{L^2(\Omega)}^2 \geq \dots$$

The goal?

$$\exists \kappa \in (0, 1) : \kappa \|\nabla(u - u_k)\|_{L^2(\Omega)}^2 \geq \|\nabla(u - u_{k+1})\|_{L^2(\Omega)}^2$$

- $\mathcal{T}_h, \mathcal{T}_H$ conforming triangulations
- \mathcal{T}_h refinement of \mathcal{T}_H
- $V_H \subseteq V_h$ the corresponding spaces
- u_h, u_H the corresponding solutions on V_h, V_H
- $e_h := u - u_h, e_H := u - u_H$

Fineness of of the triangulation

Fineness of of the triangulation \mathcal{T}_h

We say a triangulation \mathcal{T}_h has fineness μ with respect to ε if there are positive weights (w_1, w_2) for the approximation f_h such that

$$\max\{w_1\|f - f_{h'}\|_{L^2(\Omega)}, w_2\|h'f_{h'}\|_{L^2(\Omega)}\} \leq \mu\varepsilon,$$

for any refinement $\mathcal{T}_{h'}$ of \mathcal{T}_h .

Lemma 1

If

- \mathcal{T}_H has fineness μ w.r.t. ε , $w_1 = C_P$ (Poincare constant), $w_2 > 0$,
- \mathcal{T}_h is a refinement of \mathcal{T}_H ,
- there is a constant $C_e > 0$ such that

$$\|\nabla e_H\|_{L^2(\Omega)} \geq \frac{\varepsilon}{C_e},$$

then

$$\|\nabla e_H\|_{L^2(\Omega)}^2 \geq \|\nabla e_h\|_{L^2(\Omega)}^2 + \frac{1}{2} \|\nabla(u_h - u_H)\|_{L^2(\Omega)}^2 - 4C_e\mu(1 + 6C_e\mu) \|\nabla e_H\|_{L^2(\Omega)}^2.$$

Proof: Blackboard

Some blackboard computations ...

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- $\|\nabla\psi_q^k\|_{L^2(\Omega)}^2 \leq \sigma_\psi$
- $\mathcal{E}_{0,H}$ the set of interior edges in \mathcal{T}_H
- $\mathcal{R}_{0,H/2}$ be the set of midpoints on the interior edges.
- $\mathcal{R}_h \subset \mathcal{R}_{0,H/2}$ be the set of additional nodes \mathcal{T}_h .
- $[\partial_n v_H]_E$ be the jump of the normal derivative across the edge $E \in \mathcal{E}_{0,H}$.

Lemma 2

If

- $\mathcal{R}_h \subset \mathcal{R}_{0,H/2}$,
- for $q \in \mathcal{R}_h$ let $E_q \in \mathcal{E}_{0,H}$ with $q \in E_q$,

then

$$\sum_{q \in \mathcal{R}_h} d_{E_q} \| [\partial_n u_H]_E \|_{L^2(E_q)}^2 \leq 24\sigma_\psi^2 \|\nabla(u_h - u_H)\|_{L^2(\Omega)}^2 + \hat{C}_2^2 \|hf_h\|_{L^2(\Omega)}^2,$$

$$\sum_{q \in \mathcal{R}_{0,H/2}} d_{E_q} \| [\partial_n u_H]_E \|_{L^2(E_q)}^2 \leq 24\sigma_\psi^2 \|\nabla e_H\|_{L^2(\Omega)}^2 + \hat{C}_2^2 \|Hf\|_{L^2(\Omega)}^2,$$

where $\hat{C}_2^2 = 12(1 + \sigma_0^2)$.

Lemma 3

For \mathcal{T}_H it holds

$$\begin{aligned} \|\nabla e_H\|_{L^2(\Omega)} &\leq \hat{C}_3 \left(\sum_{E \in \mathcal{E}_{0,H}} d_E \|[\partial_n u_H]_E\|_{L^2(E)}^2 \right)^{\frac{1}{2}} + \hat{C}_0 \|Hf_H\|_{L^2(\Omega)} \\ &\quad + C_P \|f - f_H\|_{L^2(\Omega)}, \end{aligned}$$

where \hat{C}_3 only depends on the shape of the triangles.

Error Estimates

An error estimator

Lemma 2 and Lemma 3 suggest the following error estimate:

$$\eta_E^2 := d_E \| [\partial_n u_H]_E \|_{L^2(E)}^2$$

for $E \in \mathcal{E}_{0,H}$ or

$$\eta_T^2 := \frac{1}{2} \sum_{E \subseteq \partial T \cap \partial \Omega} d_E \| [\partial_n u_H]_E \|_{L^2(E)}^2.$$

Assumption on Refinement Strategy

- if a triangle is marked, then all 3 edges are divided!

- $\mathcal{A} \subset \mathcal{T}$
- $\eta_{\mathcal{A}}^2 := \sum_{T \in \mathcal{A}} \eta_T^2$
- \mathcal{T}_h is the resulting mesh by marking all triangles in \mathcal{A}
- $\eta_{\mathcal{A}}^2 \leq \sum_{q \in \mathcal{R}_h} \eta_{E_q}^2$
- $\eta_T^2 = \sum_{q \in \mathcal{R}_{0,H/2}} \eta_{E_q}^2$

The goal?

$$\kappa \|\nabla e_H\|_{L^2(\Omega)}^2 \geq \|\nabla e_h\|_{L^2(\Omega)}^2$$

Lemma 1

If

- \mathcal{T}_H has fineness μ w.r.t. ε , $w_1 = C_P$ (Poincare constant), $w_2 > 0$,
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- there is a constant $C_e > 0$ such that

$$\|\nabla e_H\|_{L^2(\Omega)} \geq \frac{\varepsilon}{C_e},$$

then

$$\|\nabla e_H\|_{L^2(\Omega)}^2 \geq \|\nabla e_h\|_{L^2(\Omega)}^2 + \frac{1}{2} \|\nabla(u_h - u_H)\|_{L^2(\Omega)}^2 - 4C_e\mu(1 + 6C_e\mu) \|\nabla e_H\|_{L^2(\Omega)}^2.$$

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Lemma 2

If

- $\mathcal{R}_h \subset \mathcal{R}_{0,H/2}$,
- for $q \in \mathcal{R}_h$ let $E_q \in \mathcal{E}_{0,H}$ with $q \in E_q$,

then

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$$\sum_{q \in \mathcal{R}_{0,H/2}} d_{E_q} \| [\partial_n u_H]_E \|_{L^2(E_q)}^2 \leq 24\sigma_\psi^2 \|\nabla e_H\|_{L^2(\Omega)}^2 + \hat{C}_2^2 \|Hf\|_{L^2(\Omega)}^2$$

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- $\mathcal{A} \subset \mathcal{T}$
- $\eta_{\mathcal{A}}^2 := \sum_{T \in \mathcal{A}} \eta_T^2$
- \mathcal{T}_h is the resulting mesh by marking all triangles in \mathcal{A}
- $\eta_{\mathcal{A}}^2 \leq \sum_{q \in \mathcal{R}_h} \eta_{E_q}^2$
- $\eta_T^2 = \sum_{q \in \mathcal{R}_{0,H/2}} \eta_{E_q}^2$

Lemma 2

If

- $\mathcal{R}_h \subset \mathcal{R}_{0,H/2}$,
- for $q \in \mathcal{R}_h$ let $E_q \in \mathcal{E}_{0,H}$ with $q \in E_q$,

then

$$\eta_{\mathcal{A}}^2 \leq \sum_{q \in \mathcal{R}_h} d_{E_q} \|[\partial_n u_H]_E\|_{L^2(E_q)}^2 \leq 24\sigma_\psi^2 \|\nabla(u_h - u_H)\|_{L^2(\Omega)}^2 + \hat{C}_2^2 \|hf_h\|_{L^2(\Omega)}^2,$$

$$\eta_{\mathcal{T}}^2 = \sum_{q \in \mathcal{R}_{0,H/2}} d_{E_q} \|[\partial_n u_H]_E\|_{L^2(E_q)}^2 \leq 24\sigma_\psi^2 \|\nabla e_H\|_{L^2(\Omega)}^2 + \hat{C}_2^2 \|Hf\|_{L^2(\Omega)}^2,$$

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Marking strategy

$$\eta_A \geq (1 - \theta^*)\eta_T$$

Theorem 1

Let us choose the previous marking strategy. If

- $\mu^* > 0$ and depends only on θ^* , σ_0 and H_{max}/C_P ,
- \mathcal{T}_H has fineness $\mu \leq \mu^*$ with respect to ε , $w_1 = C_P$,
 $w_2 = \max\{\hat{C}_0, \hat{C}_2\}$,

then there exists a $\kappa \in (0, 1)$ such that for the resulting triangulation \mathcal{T}_h holds

$$\|\nabla e_h\|_{L^2(\Omega)}^2 \leq \kappa \|\nabla e_H\|_{L^2(\Omega)}^2,$$

or $\eta_{\mathcal{T}} \leq \varepsilon$.

Lemma 2

If

- $\mathcal{R}_h \subset \mathcal{R}_{0,H/2}$,
- for $q \in \mathcal{R}_h$ let $E_q \in \mathcal{E}_{0,H}$ with $q \in E_q$,

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$$\eta_{\mathcal{T}}^2 = \sum_{q \in \mathcal{R}_{0,H/2}} d_{E_q} \|[\partial_n u_H]_E\|_{L^2(E_q)}^2 \leq 24\sigma_\psi^2 \|\nabla e_H\|_{L^2(\Omega)}^2 + \hat{C}_2^2 \|Hf\|_{L^2(\Omega)}^2,$$

where $\hat{C}_2^2 = 12(1 + \sigma_0^2)$.

Lemma 3

For \mathcal{T}_H it holds

$$\begin{aligned} \|\nabla e_H\|_{L^2(\Omega)} &\leq \hat{C}_3 \left(\sum_{E \in \mathcal{E}_{0,H}} d_E \|[\partial_n u_H]_E\|_{L^2(E)}^2 \right)^{\frac{1}{2}} + \hat{C}_0 \|Hf_H\|_{L^2(\Omega)} \\ &\quad + C_P \|f - f_H\|_{L^2(\Omega)}, \end{aligned}$$

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If

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$$\|\nabla e_h\|_{L^2(\Omega)}^2 \leq \kappa \|\nabla e_H\|_{L^2(\Omega)}^2,$$

or $\eta_{\mathcal{T}} \leq \varepsilon$.

Holds also for the residual error estimator

$$\eta_{\mathcal{T}}^R := (\eta_{\mathcal{T}}^2 + s_0^2 \|Hf_H\|_{L^2(T)}^2)^{\frac{1}{2}}.$$

$$(\eta_{\mathcal{T}}^R := (\eta_{\mathcal{T}}^2 + s_0^2 \|H(\Delta u_H + f_H)\|_{L^2(T)}^2)^{\frac{1}{2}} \text{ for higher order elements})$$

Locally equivalent error estimators

Locally equivalent

We say an error estimator is locally equivalent to the residual error estimator if

- sets $S'_T, S''_T \subset \mathcal{T}$,
- constants $C'_\tilde{\eta}, C''_\tilde{\eta}$,

such that for all $T \in \mathcal{T}$ holds

- $\tilde{\eta}_T \leq C'_\tilde{\eta} \eta_{S'_T}^R$,
- $\eta_T^R \leq C''_\tilde{\eta} \tilde{\eta}_{S''_T}$.

Modified refinement strategy

- if a triangle T is marked, then all 3 edges of all triangles contained in S'_T are divided.

Theorem 2

Let us choose the previous marking strategy. If

- $\tilde{\eta}$ is locally equivalent to η^R

then Theorem 1 also holds for $\tilde{\eta}$, with different constants.

Initial Mesh

Construction of an initial mesh with fineness μ

$$\eta_T^0 := \max\{w_1 \|f - f_h\|_{L^2(T)}, w_2 \|hf_h\|_{L^2(T)}\},$$

- use same marking and refinement strategy as for η
- stop wenn $\eta_{T_0}^0 \leq \mu\epsilon$.

References



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Thank you for your Attention!